



Software Engineering Conference Russia

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Autonomous driving

Why don't we still have it?

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EPAM

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**Computer Vision, Machine Learning,
Robotics, AI**

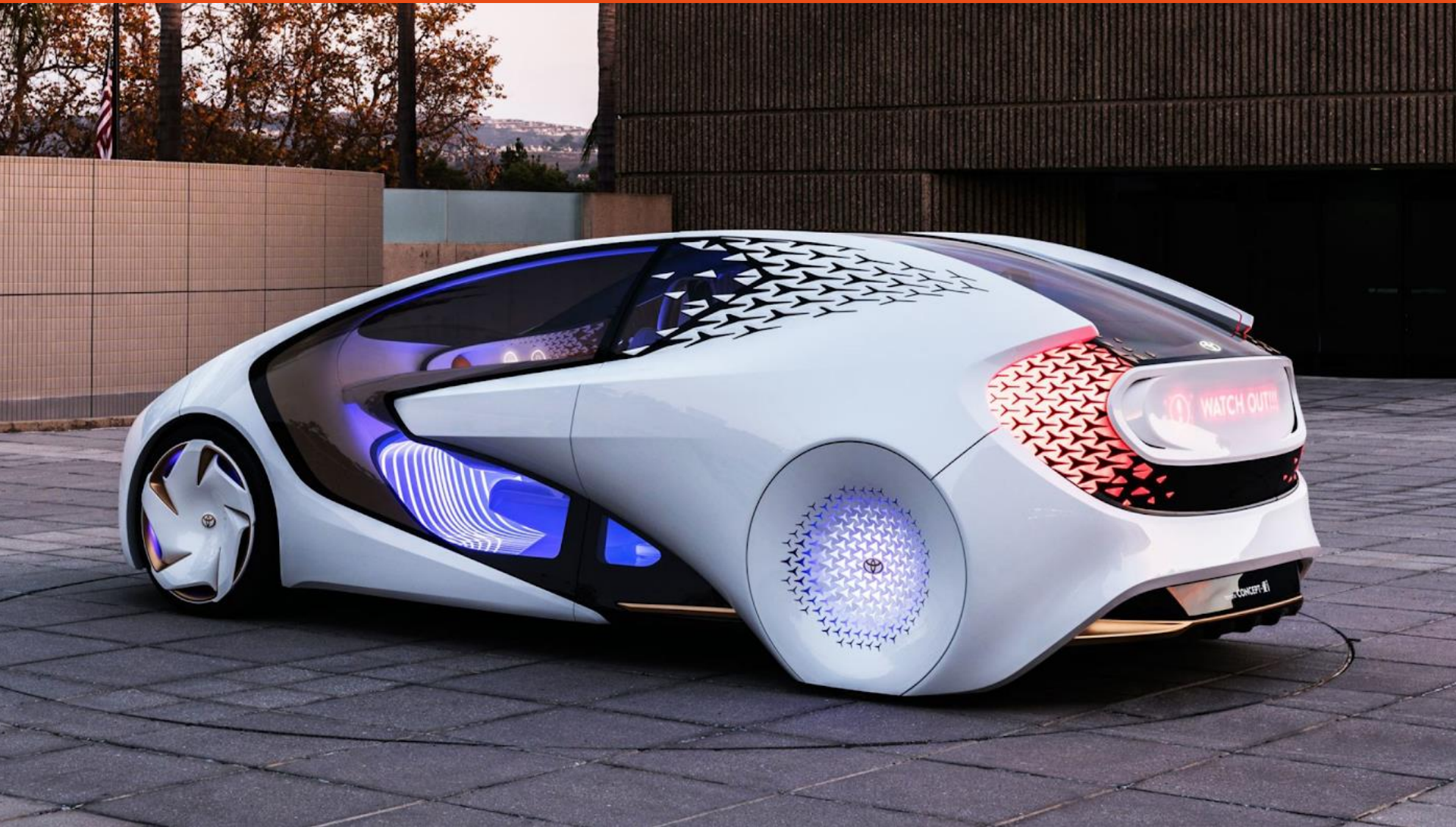
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What did we expect



What do we have



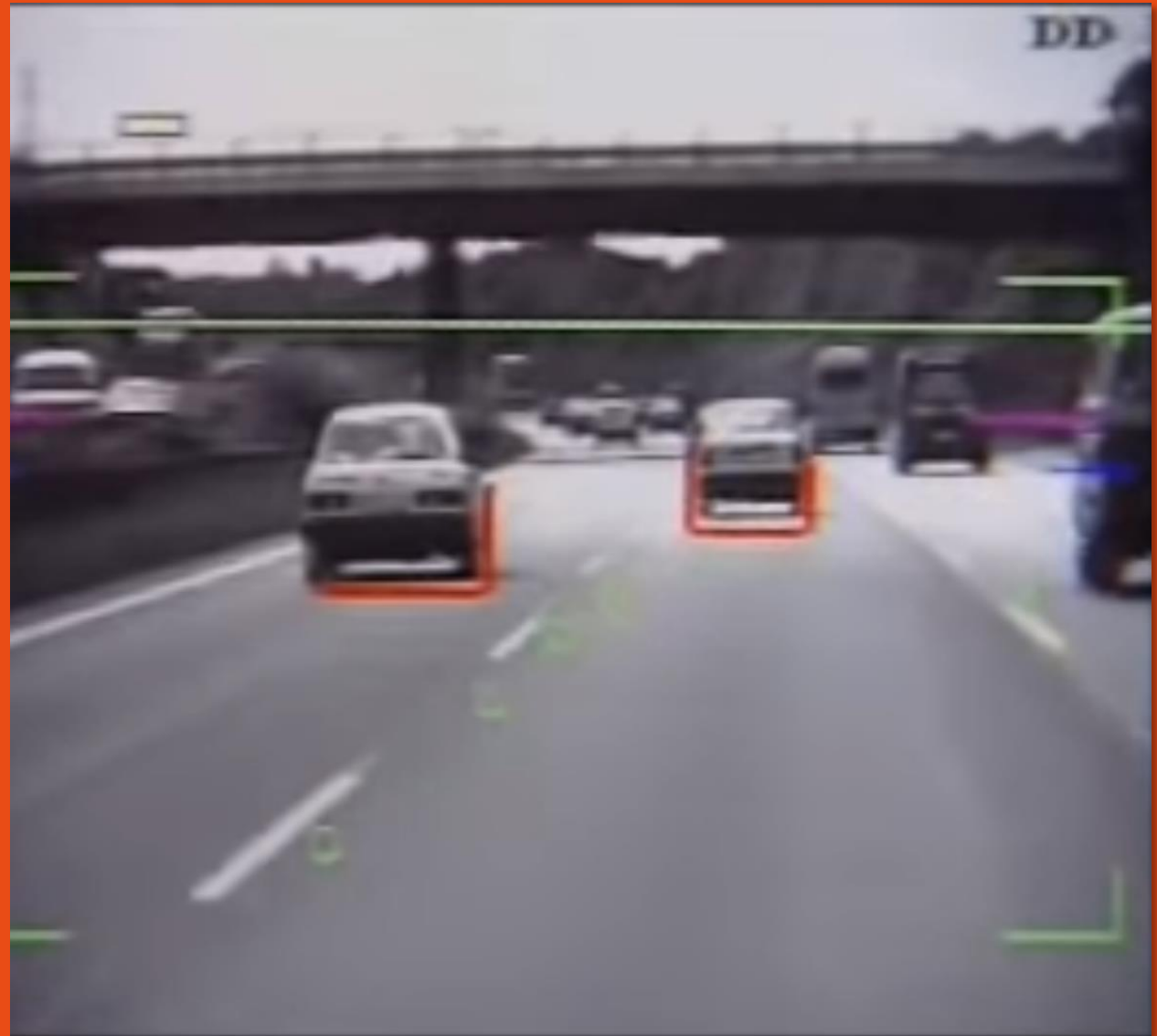


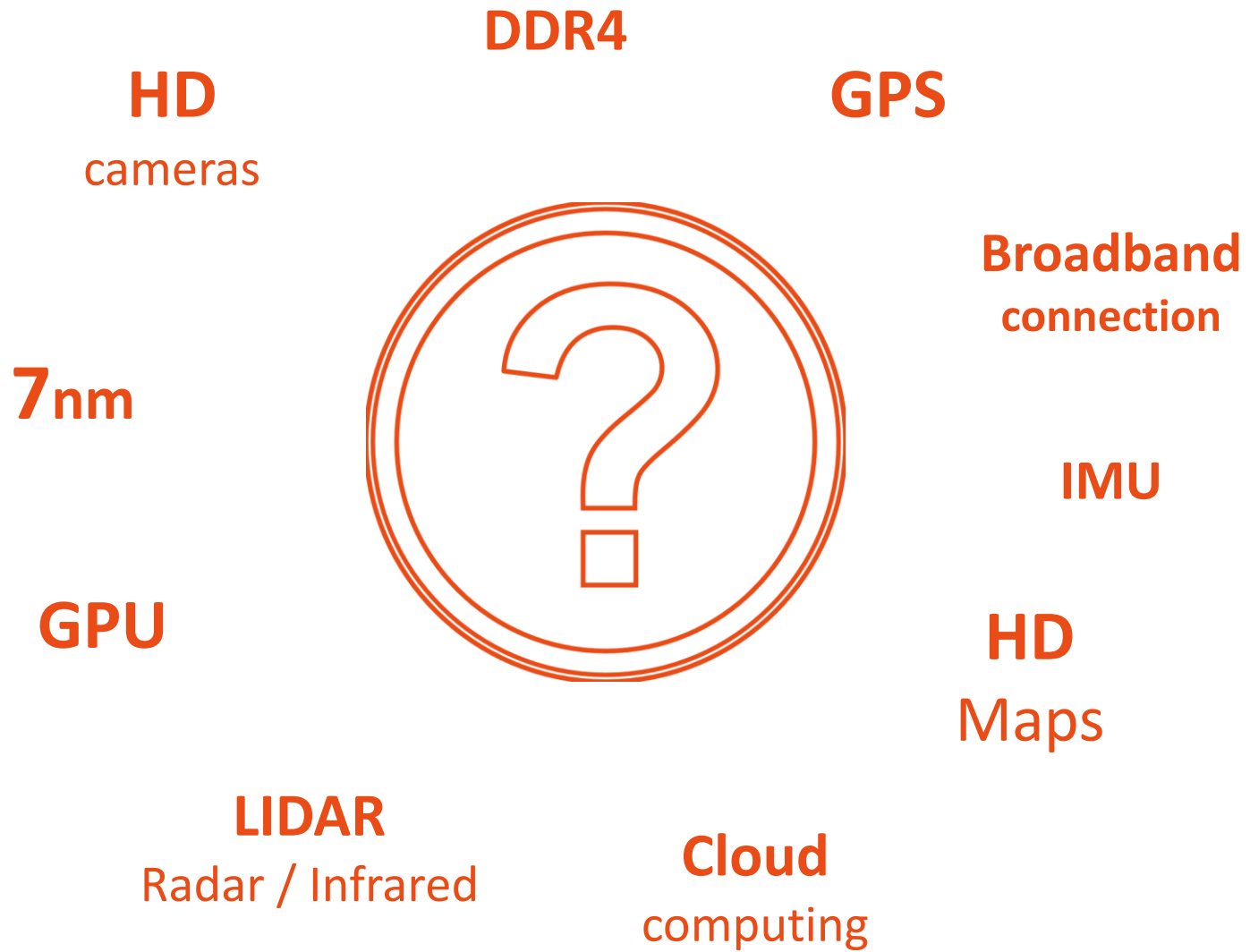
1994

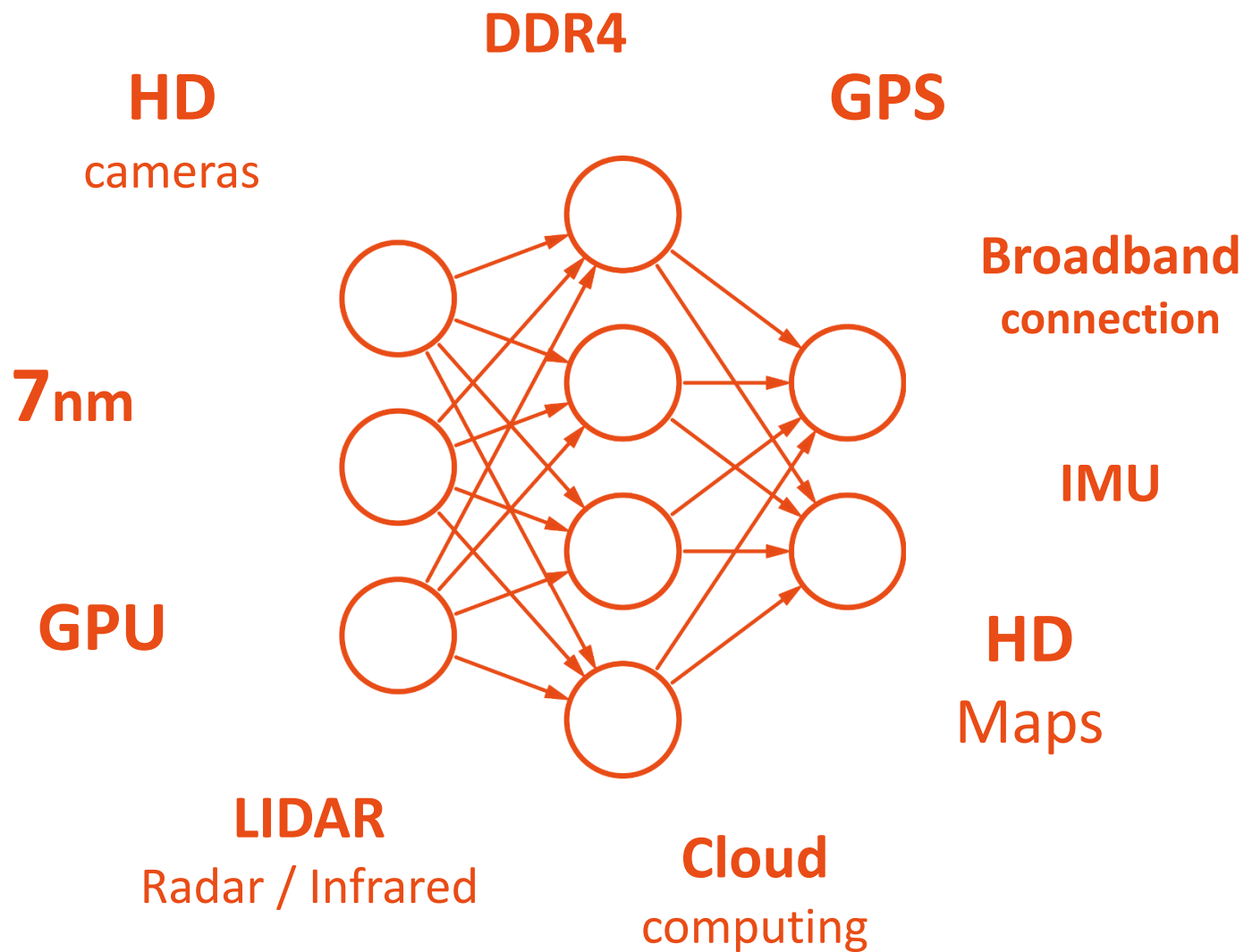
Ernst Dickmann

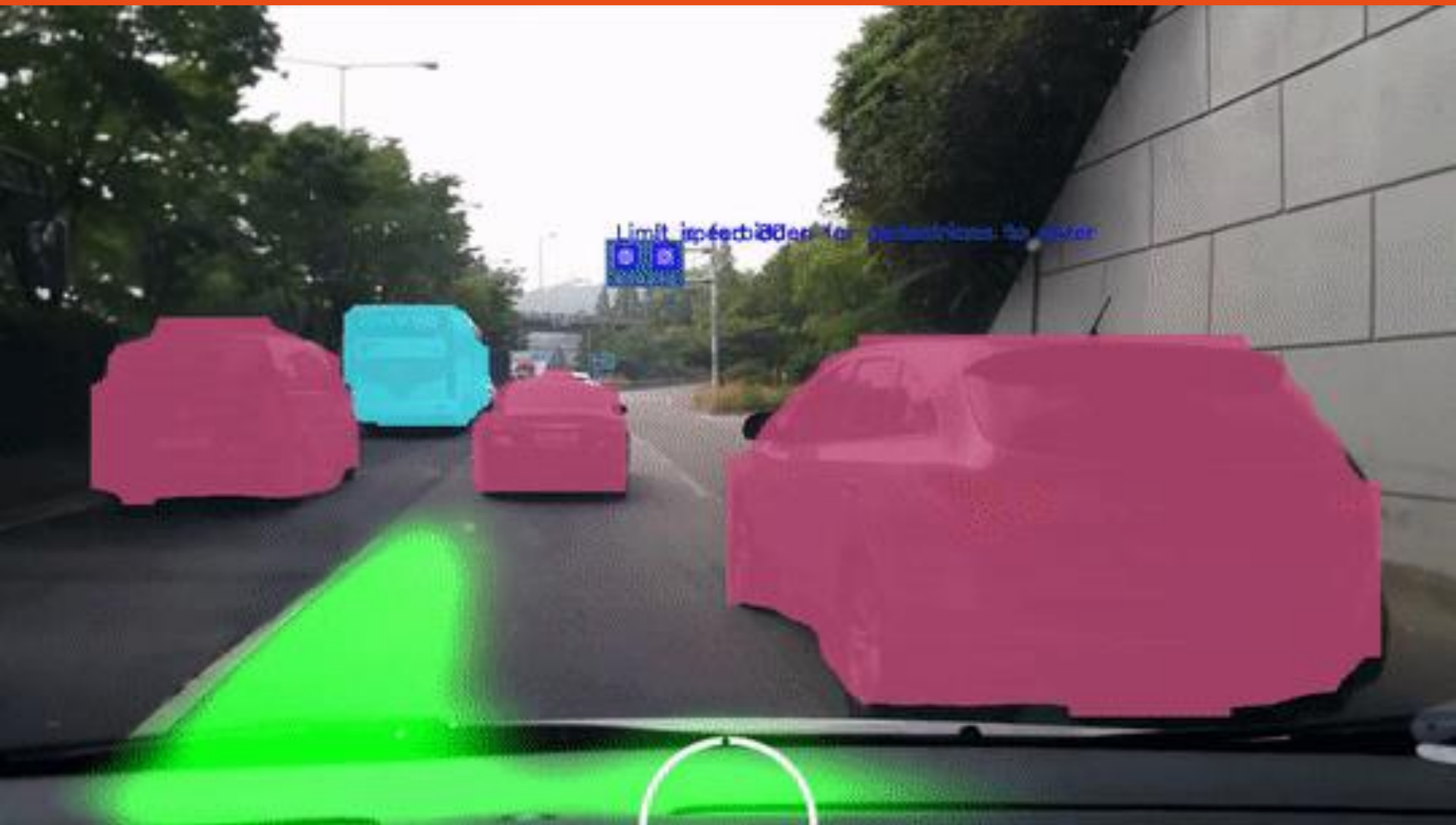
Universität der Bundeswehr
München

- Up to 130 km/h
- Up to 1600 km
- Lane tracking
- Lane change
- Obstacles tracking









Limit is forbidden for vehicles to enter









Eye vs Camera



~256 Mp
Effective 500-600 Mp
Dynamic range 2^{24}



Full HD / 4K / 8K
Dynamic range 2^{10}

UBER

Top mounted lidar units provide a 360° 3-dimensional scan of the environment.

Forward facing camera array focus both close and far field, watching for breaking vehicles, crossing pedestrians, traffic lights, and signage.

Side and rear facing stereo camera pairs work in collaboration to construct a continuous view of the vehicle's surroundings

Roof and trunk mounted antennae provide GPS positioning and wireless data capabilities.



360° radar coverage

Front, rear, and wing mounted lidar modules aide in the detection of obstacles in close proximity to the vehicle as well as smaller ones that can get lost in blind spots.

Custom designed compute and storage allow for real-time processing of data. A fully integrated cooling solution keeps components running optimally.



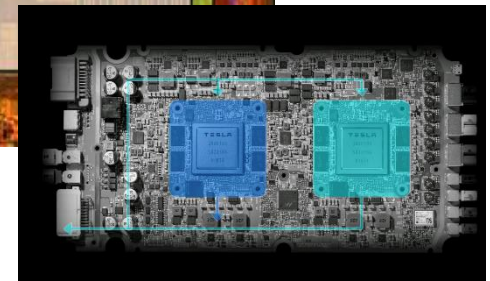
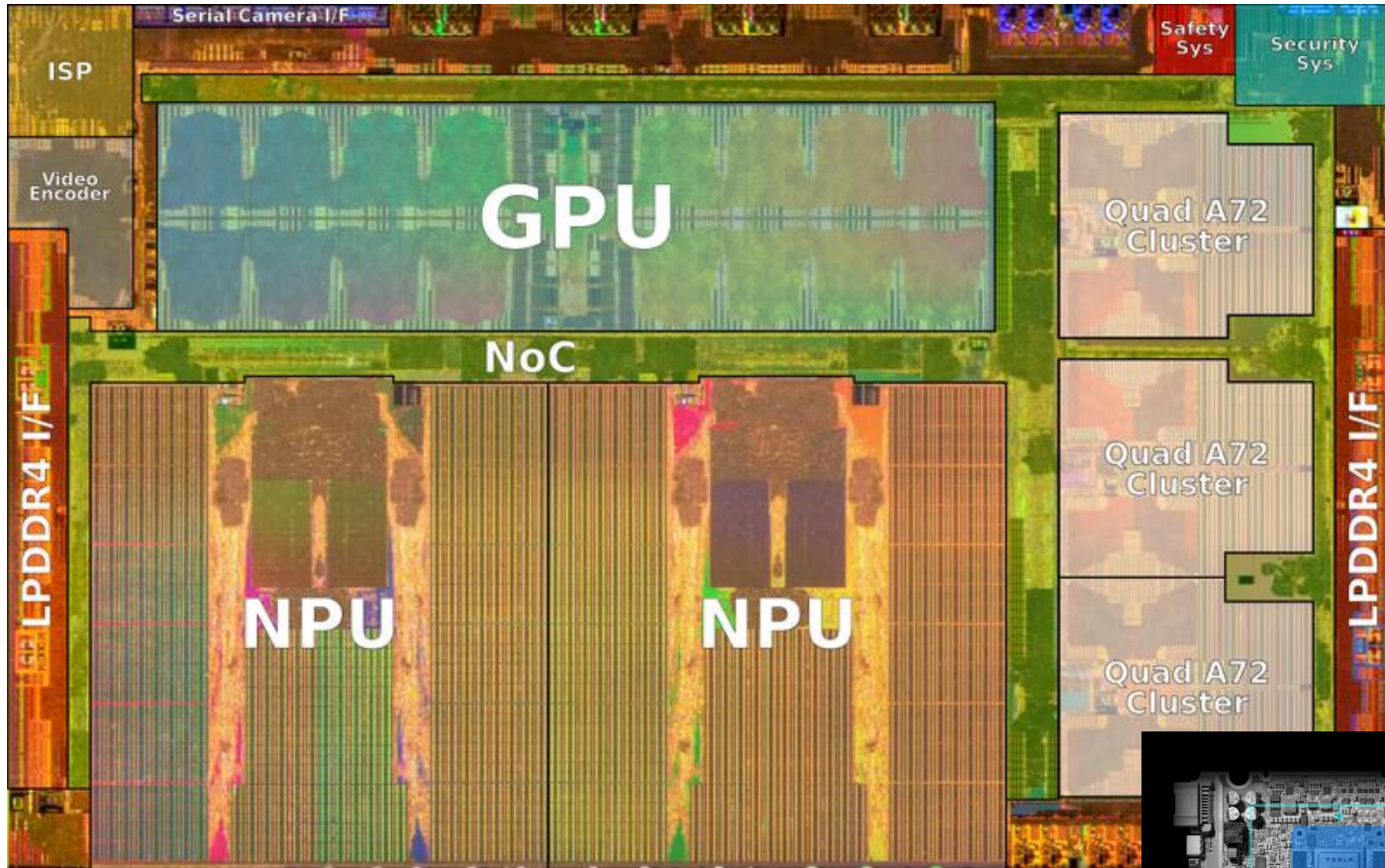








Custom HW is Key



TESLA NXP ARM NVIDIA HUAWEI

Performance • Power consumption • Latency • Heat • Size

Architecture

Perception

3D
Reconstruction

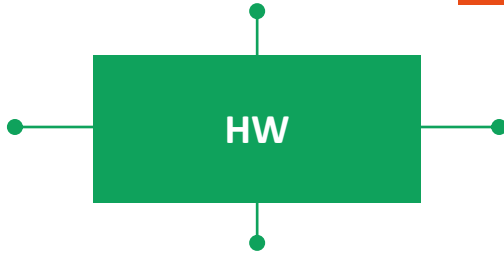
Object
Detection

Image
Processing

Distance
Estimation

Sensors

Sensor
Integration



Understanding

Context
Analysis

Time-domain
Analysis

Localization
Mapping

GPS

Maps



Planning

Prediction

Context
Analysis

Agent Models

Trajectory
Planning

Command
Pipeline

Road
Condition

Activators

Sensors

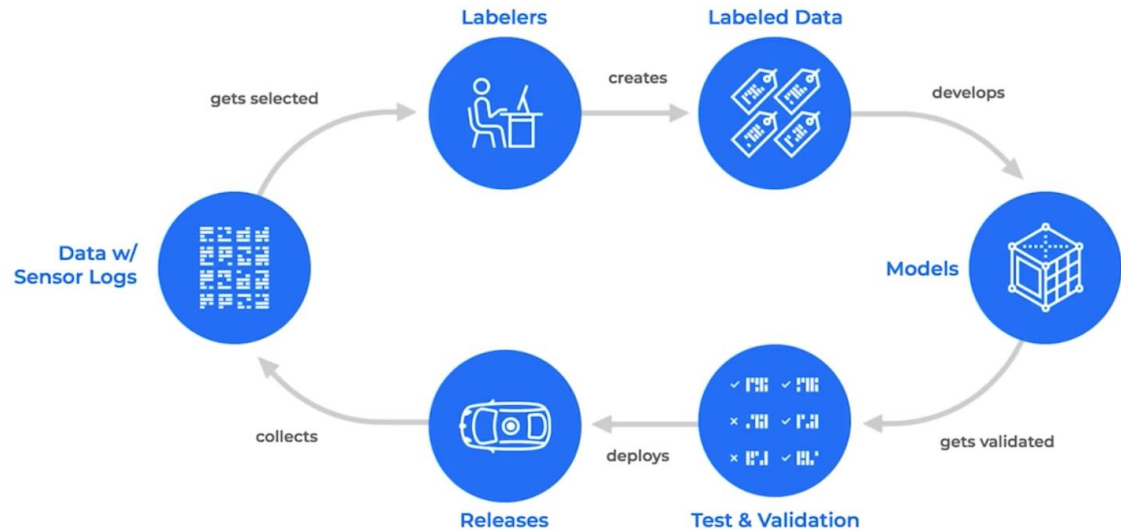
Two ways



Full Autonomy



Machine Learning Cycle



Source: Waymo



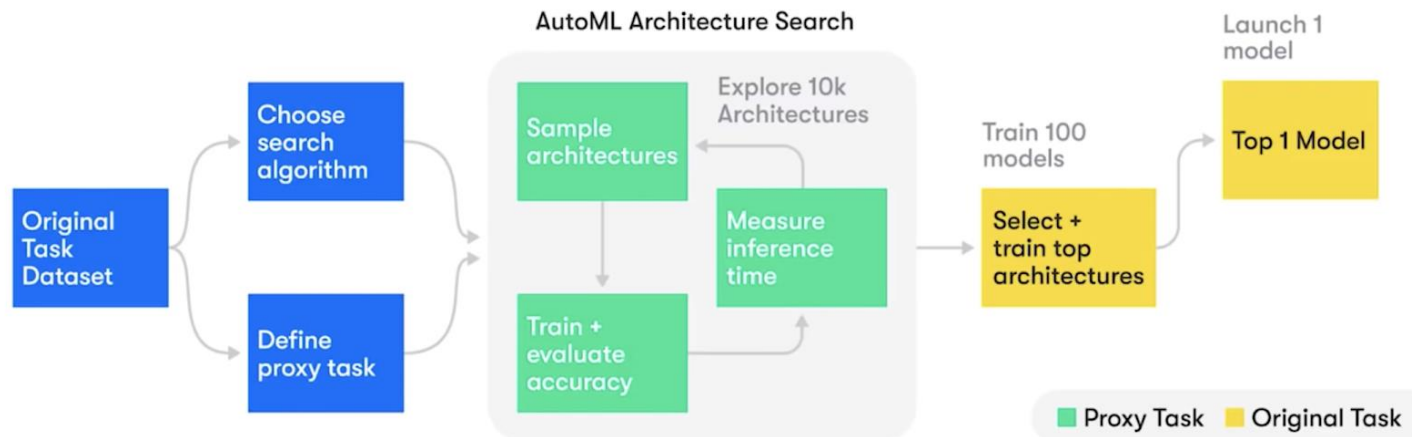
- **1,5B Real Self-Driving Miles Driven**
- **500K AD Capable Cars on Public Roads**



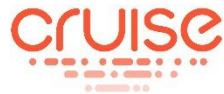
- **25K Simulated Cars 24/7**
- **7B+ Simulated Miles**
- **100M Real Self-Driving Miles**

Auto ML

End-to-end architecture search



Source: Waymo





The End



The End Beginning